

## Comments on Numerical Integration

- Using Newton-Cotes Formulas we use  $(n+1)$  equally spaced sampling points to exactly integrate a polynomial of at most order  $n$
- Using Gauss Quadrature we require  $n$  equally spaced sampling pts to exactly integrate a polynomial of at most order  $(2n-1)$
- To integrate a quadratic polynomial i.e.  $n=2$  will need  $n+1=3$  sampling pts using Newton-Cotes
- Correspondingly in Gauss Quadrature polynomial order  $2n-1=2 \Rightarrow n = \frac{3}{2}$  2 pts.
- if polynomial order  $2n-1=3 \Rightarrow n=2$  pts. Correspondingly Newton-Cotes will require 4 pts to exactly integrate a cubic polynomial

### Example

Use 2pt Gauss Quadrature to evaluate

$$\int_0^3 (2^r - r) dr$$

$$\int_0^3 (2^r - r) dr = \alpha_1 F(r_1) + \alpha_2 F(r_2)$$

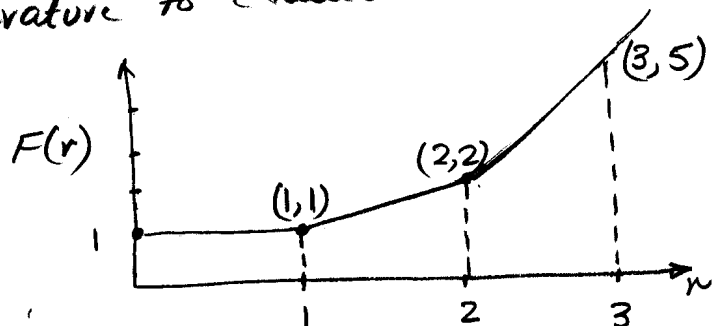
$\alpha_1, \alpha_2 =$  weights

$r_1, r_2 =$  sampling pts

$$\alpha_1 = \alpha_2 = \frac{3-0}{2} \times 1 = \frac{3}{2}, \quad w_1 = \frac{3}{2} \left(1 - \frac{1}{\sqrt{3}}\right) = 0.63397$$

$$r_2 = \frac{3}{2} \left(1 + \frac{1}{\sqrt{3}}\right) = 2.36603$$

$$\int_0^3 (2^r - r) dr \approx \frac{3}{2} \left( 2^{0.63397} - 0.63397 \right) + \frac{3}{2} \left( 2^{2.36603} - 2.36603 \right) = \boxed{5.56055}$$



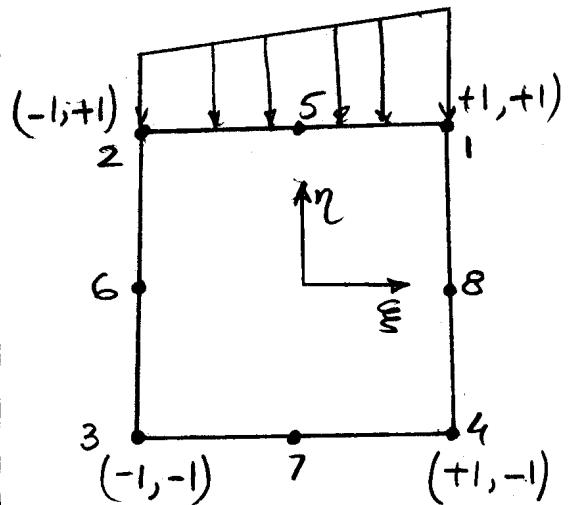
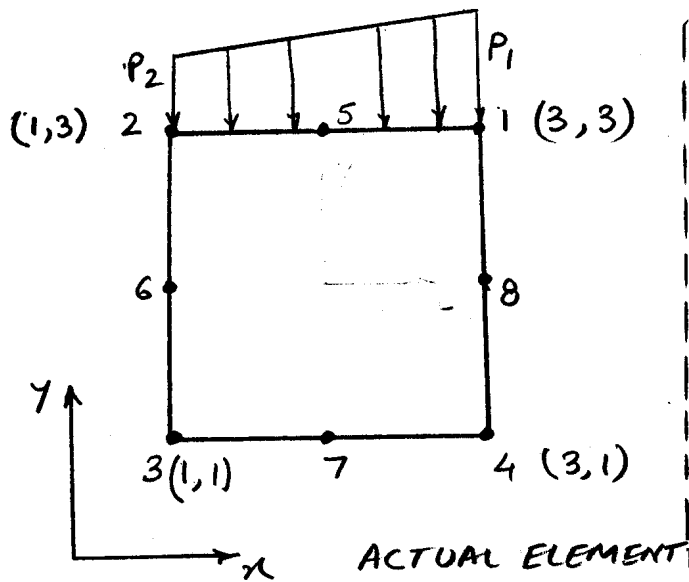
# Comments on Numerical Integration

## Example Problem

Exact Solution

$$\begin{aligned}\int_0^3 (2^x - x) dx &= \left| \frac{2^x}{\ln 2} - \frac{x^2}{2} \right|_0^3 \\ &= \frac{2^3}{\ln 2} - \frac{2^0}{\ln 2} - \frac{3^2}{2} \\ &= 11.54156 - 1.44269 - \frac{9}{2} \\ &= 5.59887 \text{ exact} \approx 5.56055 \text{ Numerical} \\ \underline{\% \text{ error} = 0.7\%}\end{aligned}$$

## Example Problem



For the 2-D element shown above calculate the Jacobian Matrix of Transformation from Cartesian coordinates to natural coordinates.

Evaluate the consistent Nodal loads corresponding to the surface loading shown

$$\xi = \frac{x - \frac{x_1 + x_2}{2}}{(x_1 - x_2)/2} = \frac{2x - x_1 - x_2}{(x_1 - x_2)}$$

$$\eta = \frac{y - \frac{y_1 + y_4}{2}}{(y_1 - y_4)/2} = \frac{2y - y_1 - y_4}{(y_1 - y_4)}$$

$$\frac{\partial f}{\partial \xi} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \xi} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \xi}$$

$$\frac{\partial f}{\partial \eta} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial \eta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \eta}$$

## Example Problem

$$\begin{Bmatrix} \frac{\partial f}{\partial \xi} \\ \frac{\partial f}{\partial \eta} \end{Bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} \begin{Bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{Bmatrix}$$

$[J]$  Jacobian Matrix

$$\xi = \frac{2x - x_1 + x_2}{x_1 - x_2} = \frac{2x - 3 - 1}{3 - 1} = \frac{2x - 4}{2}$$

$$\Rightarrow 2x - 4 = 2\xi$$

$$\Rightarrow \boxed{x = \frac{2\xi + 4}{2} = \xi + 2}$$

$$\eta = \frac{2y - y_1 - y_2}{y_1 - y_2} = \frac{2y - 3 - 1}{3 - 1} = \frac{2y - 4}{2}$$

$$\boxed{y = \eta + 2}$$

$$\frac{\partial x}{\partial \xi} = 1, \quad \frac{\partial x}{\partial \eta} = 0$$

$$\frac{\partial x}{\partial \eta} = 0, \quad \frac{\partial y}{\partial \eta} = 1$$

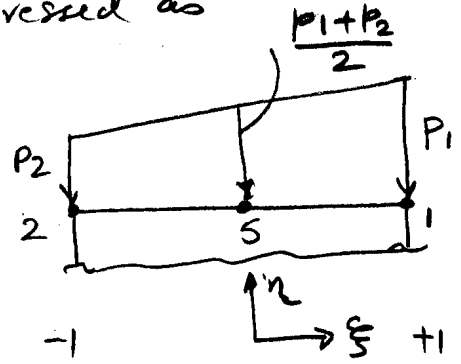
$$\Rightarrow J = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\text{Det}[J] = 1$$

## Example Problem

The pressure variation can be expressed as

$$f_{\eta} = \frac{P_1 + P_2}{2} + \frac{P_1 - P_2}{2} \xi$$



Work Equivalent Nodal Forces at Nodes 1, 2, & 5 are found as follows

$$\{P\} = \int_{-1}^{+1} t \begin{bmatrix} N_1 & 0 \\ N_2 & 0 \\ \vdots & \vdots \\ N_5 & 0 \\ N_6 & 0 \\ \hline 0 & N_1 \\ 0 & N_2 \\ \vdots & \vdots \\ 0 & N_6 \end{bmatrix} \left\{ \begin{matrix} 0 \\ \frac{P_1 + P_2}{2} + \frac{P_1 - P_2}{2} \xi \end{matrix} \right\} d\xi$$

The above integral needs to be evaluated on edge 1 → 5 → 2 on which all  $N_i$  would be = 0 except for  $N_1, N_5, N_2$

On edge 1 → 5 → 2  $\eta = 1$  so

$$\begin{aligned} N_1(\xi, \eta) &= N_1(\xi, \eta=1) = \frac{1}{4}(1+\xi)(1+\eta) - \frac{1}{2}(N_6 + N_7) \\ &= \frac{1}{4}(1+\xi)(2) - \frac{1}{2}\left(\frac{1}{2}(1-\xi^2)2\right) \\ &= \frac{1}{2}(1+\xi) - \frac{1}{2}(1-\xi^2) \\ &= \frac{1}{2}(1+\xi)(1 - (1-\xi)) \\ &= \frac{1}{2}\xi(1+\xi) \end{aligned}$$

$$\begin{aligned}
 N_2 &= \frac{1}{4} (1-\xi)(1+\eta) - \frac{1}{2} (N_7 + N_8) \\
 &= \frac{1}{4} (1-\xi)(2) - \frac{1}{2} \left( \frac{1}{2} (1-\xi^2)(2) \right) \\
 &= \frac{1}{2} (1-\xi) - \frac{1}{2} (1-\xi^2) \\
 &= \frac{1}{2} (1-\xi) (1 - (1+\xi))
 \end{aligned}$$

$$N_2 = -\frac{1}{2} \xi (1-\xi)$$

$$N_5 \equiv N_7 = \frac{1}{2} (1-\xi^2)(1+\eta) = \frac{1}{2} (1-\xi^2)(1+1)$$

$$N_5 = (1-\xi^2)$$

Hence the vertical Dir Nodal Loads for nodes 1, 2 & 5 are

$$\begin{Bmatrix} P_{1y} \\ P_{2y} \\ P_{5y} \end{Bmatrix} = \int_{-1}^{+1} t \begin{Bmatrix} N_1 \\ N_2 \\ N_5 \end{Bmatrix} \left[ \frac{p_1+p_2}{2} + \frac{p_1-p_2}{2} \xi \right] d\xi$$

$$= t \int_{-1}^{+1} \begin{Bmatrix} \frac{1}{2} \xi (1+\xi) \\ -\frac{1}{2} \xi (1-\xi) \\ (1-\xi^2) \end{Bmatrix} \left[ \frac{p_1+p_2}{2} + \frac{p_1-p_2}{2} \xi \right] d\xi$$

# Example Problem

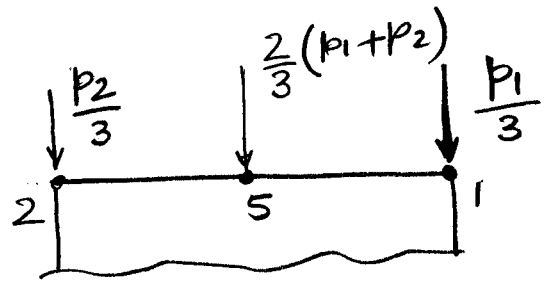
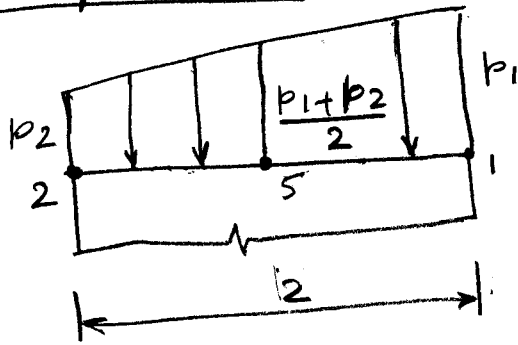
$$\begin{Bmatrix} P_{1y} \\ P_{2y} \\ P_{3y} \end{Bmatrix} = t \int_{-1}^{+1} \left\{ \begin{array}{l} \frac{p_1+p_2}{4} (\xi + \xi^2) + \frac{p_1-p_2}{4} (\xi^2 + \xi^3) \\ \frac{p_1+p_2}{4} (-\xi + \xi^2) + \frac{p_1-p_2}{4} (-\xi^2 + \xi^3) \\ \frac{p_1+p_2}{2} (1 - \xi^2) + \frac{p_1-p_2}{2} (\xi - \xi^3) \end{array} \right\} d\xi$$

$$= t \left[ \begin{array}{cc} \frac{\xi^2}{2} + \frac{\xi^3}{3} & \frac{\xi^3}{3} + \frac{\xi^4}{4} \\ -\frac{\xi^2}{2} + \frac{\xi^3}{3} & -\frac{\xi^3}{3} + \frac{\xi^4}{4} \\ 2(\xi - \frac{\xi^3}{3}) & 2(\frac{\xi^2}{2} - \frac{\xi^4}{4}) \end{array} \right]_{-1}^{+1} \begin{Bmatrix} \frac{p_1+p_2}{4} \\ \frac{p_1-p_2}{4} \end{Bmatrix}$$

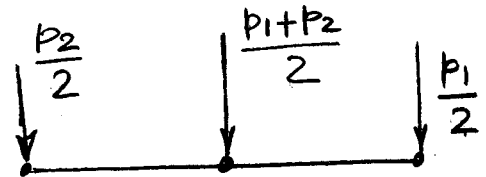
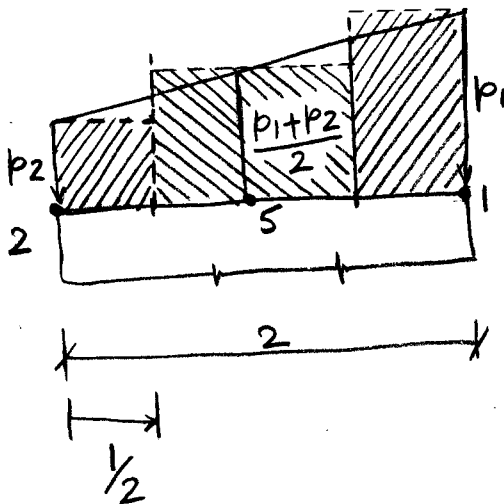
$$= t \left[ \begin{array}{cc} \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} \\ 2(2 - \frac{2}{3}) & 0 \end{array} \right] \begin{Bmatrix} \frac{p_1+p_2}{4} \\ \frac{p_1-p_2}{4} \end{Bmatrix}$$

$$= t \left\{ \begin{array}{l} \frac{2(p_1+p_2)}{12} + \frac{2(p_1-p_2)}{12} \\ \frac{2(p_1+p_2)}{12} - \frac{2(p_1-p_2)}{12} \\ \frac{8}{12}(p_1+p_2) \end{array} \right\} = t \begin{Bmatrix} \frac{1}{3} p_1 \\ \frac{1}{3} p_2 \\ \frac{2}{3}(p_1+p_2) \end{Bmatrix}$$

## Example Problem



WORK EQUIVALENT  
NODAL LOADS



NODAL LOADS  
BASED ON TRIBUTARY AREAS

$$\begin{array}{l} \text{Total Pressure} \\ \text{Force} \end{array} = \frac{p_1 + p_2}{2} \times 2 = p_1 + p_2$$

$$\begin{array}{l} \text{Sum Work Equiv.} \\ \text{Nodal Forces} \end{array} = \frac{p_2}{3} + \frac{2}{3}(p_1 + p_2) + \frac{p_1}{3} = p_1 + p_2$$

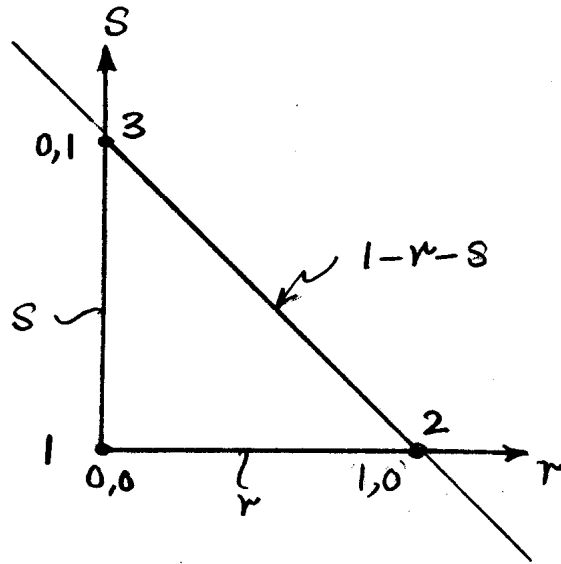
$$\begin{array}{l} \text{Sum Tributary} \\ \text{Area Est. Loads} \end{array} = \frac{p_2}{2} + \frac{p_1 + p_2}{2} + \frac{p_1}{2} = p_1 + p_2$$

Both the work equivalent nodal loads and the tributary area based nodal loads satisfy equilibrium.



# ISOPARAMETRIC TRIANGULAR ELEMENTS

## 3-Noded Triangle



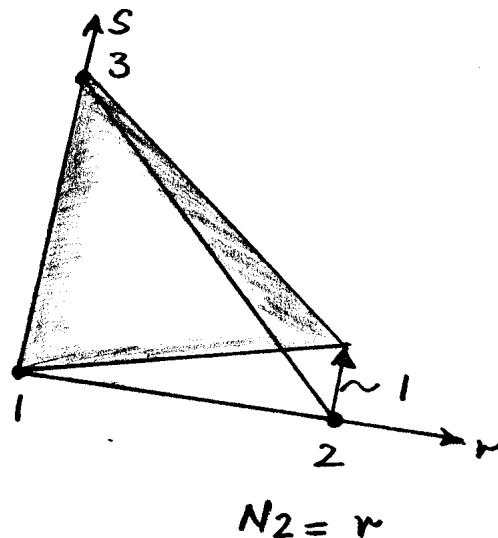
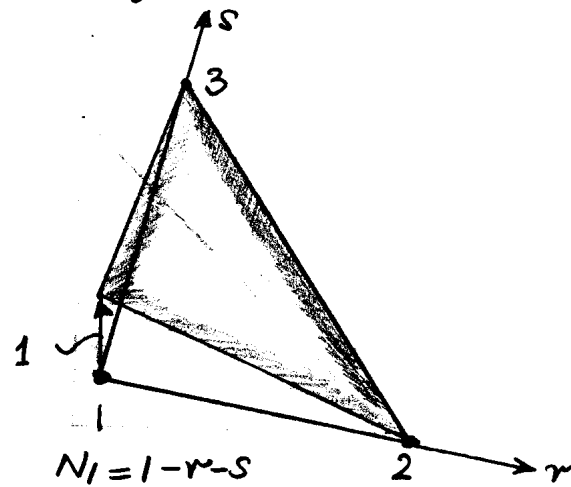
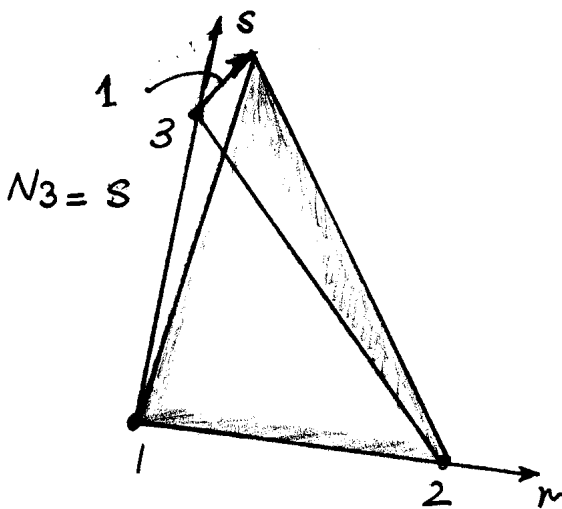
Shape Function for node 1 can be obtained by the equation of line passing through Nodes 2-3

Thus

$$N_1 = 1 - r - s$$

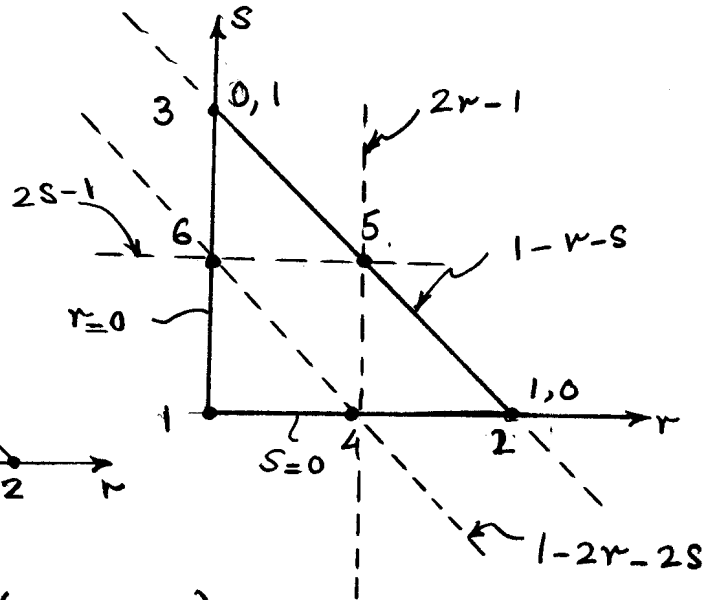
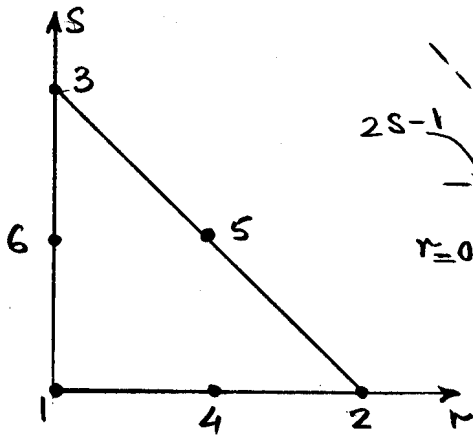
$$N_2 = r$$

$$N_3 = s$$



# ISOPARAMETRIC TRIANGULAR ELEMENTS

## 6-Noded Triangle



$$N_1 = (1-r-s)(1-2r-2s)$$

$$N_2 = r(2r-1)$$

$$N_3 = s(2s-1)$$

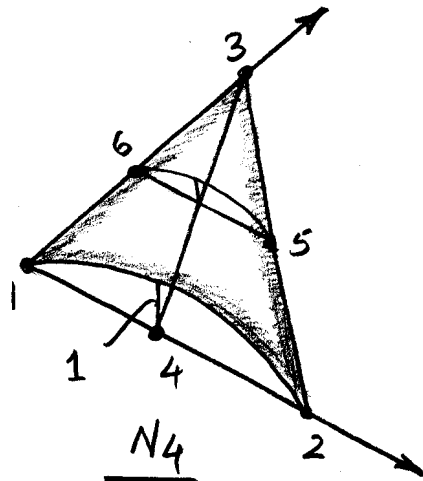
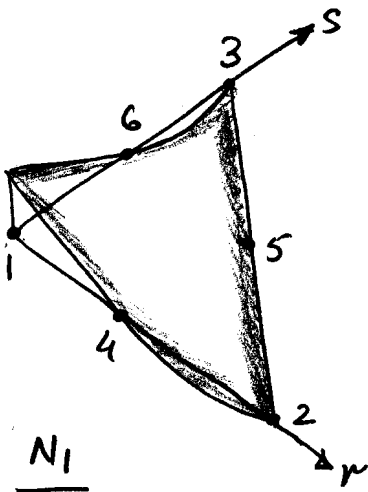
$$N_4 = r(1-r-s)$$

$$= \frac{1}{2} \left( 1 - \frac{1}{2} - 0 \right) = \frac{1}{4} \Rightarrow N_1$$

$$\Rightarrow N_4 = 4r(1-r-s)$$

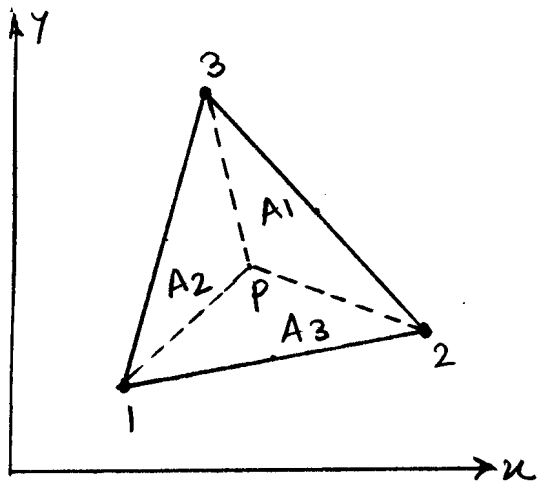
$$N_5 = 4rs$$

$$N_6 = 4s(1-r-s)$$



## TRIANGULAR ELEMENTS AREA COORDINATES

For Triangular Elements if their edges are straight and the nodes are uniformly spaced it is possible to write their shape functions using "Area Coordinates". Furthermore, it is possible in such case to evaluate the various integrals required for Finite Element Solution using analytical Formulas as the Jacobian Matrix for the mapping is constant.



The position of any Pt "P" within the triangle can be described in terms of area coordinates. The Pt "P" divides the triangle into 3 sub-areas the ratios of which to the total area of the triangle are called "Area Coordinates"

Area Coordinates of Pt "P"

$$L_1 = \frac{A_1}{A}, \quad L_2 = \frac{A_2}{A}, \quad L_3 = \frac{A_3}{A}$$

A = Total area of Triangle

$$L_1 + L_2 + L_3 = \frac{A_1}{A} + \frac{A_2}{A} + \frac{A_3}{A} = 1$$

## Triangular Elements & Area Coordinates

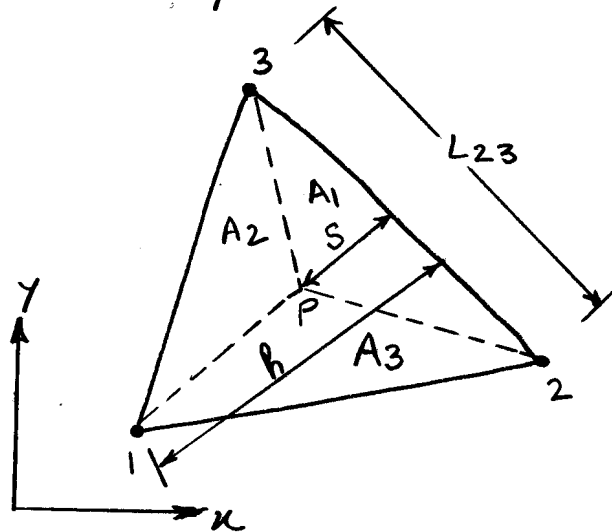
The centroid of a straight sided triangle is located at area coordinates

$$L_1 = L_2 = L_3 = \frac{1}{3}$$

in Cartesian coordinates the centroid is located at

$$\frac{x_1 + x_2 + x_3}{3} \quad \text{and} \quad \frac{y_1 + y_2 + y_3}{3}$$

Area coordinates can also be expressed as ratios of lengths



$$A_1 = \frac{L_{23} S}{2}$$

$$A = \frac{L_{23} h}{2}$$

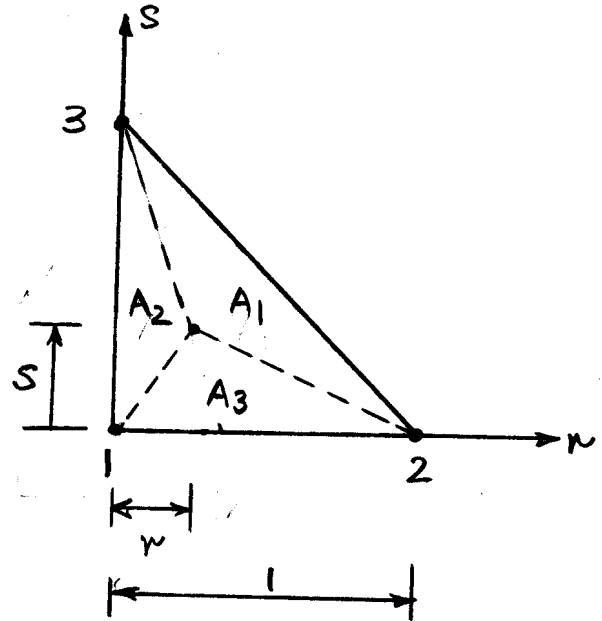
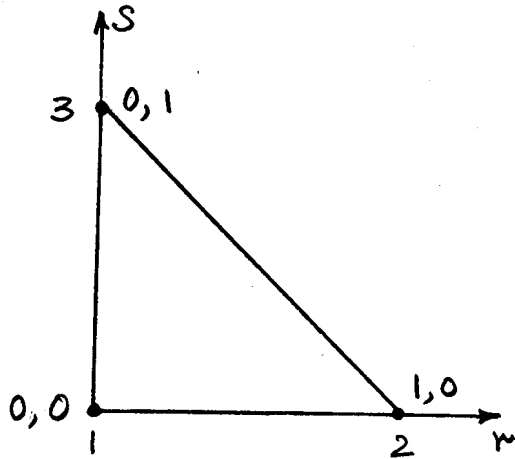
$$L_1 = \frac{A_1}{A} = \frac{L_{23} S}{2} \times \frac{2}{L_{23} h}$$

$$L_1 = \frac{A_1}{A} = \frac{S}{h}$$

# Triangular Elements & Area Coordinates

## Relation Between Area Coords & Isoparametric Coords

The relation between Area Coordinates  $L_i$  and Isoparametric Shape Functions for triangular elements is easily establishable if we consider Area coordinates as ratios of lengths.



$$A_2 = \frac{1 \cdot r}{2} = \frac{r}{2}$$

$$A_3 = \frac{1 \cdot s}{2} = \frac{s}{2}$$

$$A = \frac{1}{2}$$

$$L_2 = \frac{A_2}{A} = \frac{\frac{r}{2}}{\frac{1}{2}} = r$$

$$L_3 = \frac{A_3}{A} = \frac{\frac{s}{2}}{\frac{1}{2}} = s$$

$$L_1 = 1 - L_2 - L_3 = 1 - r - s$$

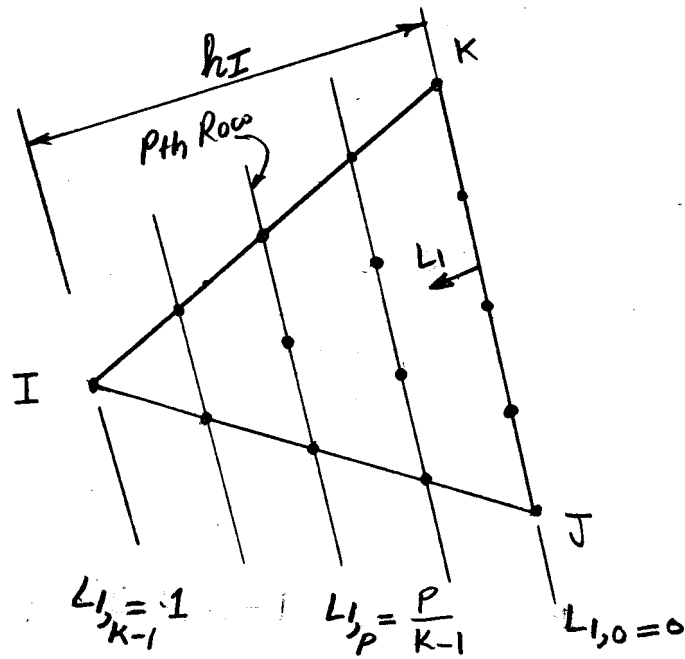
In this case the area coordinates are equal to shape functions in parametric coordinates.

$$L_1 = N_1(r,s)$$

$$L_2 = N_2(r,s)$$

$$L_3 = N_3(r,s)$$

# Area Coordinates for Higher Order Triangular Elements



Consider the higher order triangular element shown above containing "k" number of nodes per side that are equally spaced. Then the total number of nodes in the element is:

$$n = \sum_{i=0}^{k-1} (k-i) = k + (k-1) + (k-2) + \dots + 1 = \frac{1}{2} k(k+1)$$

The degree of interpolation Function is  $k-1$

The Corner nodes are denoted by I, J and K

$h_I$  = Perpendicular distance of node I from side JK

If  $L_{1,0} = 0 = L_1$  Coord of line JK

$L_{1,k-1} = 1 = L_1$  Coord of Corner Node I

Then if nodes are equally spaced

$$L_{1,p} = L_1 \text{ Coord of } p\text{th Row from JK} = \frac{p}{k-1}$$

## Area Coordinates for Higher Order Triangular Elements

The interpolation Shape Function for the corner node  
 $I$  should be zero everywhere except @  $I_{1,k-1}$

Using the Lagrangian Interpolation formula we  
can write

$$N_{aI} = \prod_{\substack{p=0 \\ p \neq k-1}}^{k-1} \frac{L_I - L_{1,p}}{L_I - L_{1,p}}$$

$$N_{aI} = \frac{(L_I - L_{1,0})(L_I - L_{1,1}) \dots (L_I - L_{1,k-2})}{(L_I - L_{1,0})(L_I - L_{1,1}) \dots (L_I - L_{1,k-2})}$$

## Area Coordinates For Triangular Elements

Similarly

$$N_{a3} = L_3(2L_3 - 1)$$

$$N_{a4} = L_1 L_2$$

$$N_{a4} \Big|_{\text{Node 4}} = \frac{1}{2} \times \frac{1}{2} = \frac{1}{4}$$

$$\Rightarrow N_{a4} = 4 L_1 L_2$$

Similarly

$$N_{a5} = 4 L_2 L_3$$

$$N_{a6} = 4 L_1 L_3$$

Summarizing The shape Functions in area coordinates are

$$N_{a1} = L_1(2L_1 - 1)$$

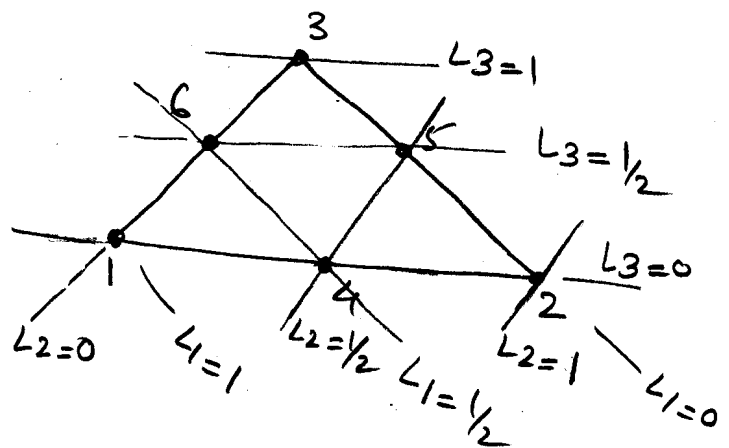
$$N_{a2} = L_2(2L_2 - 1)$$

$$N_{a3} = L_3(2L_3 - 1)$$

$$N_{a4} = 4 L_1 L_2$$

$$N_{a5} = 4 L_2 L_3$$

$$N_{a6} = 4 L_1 L_3$$

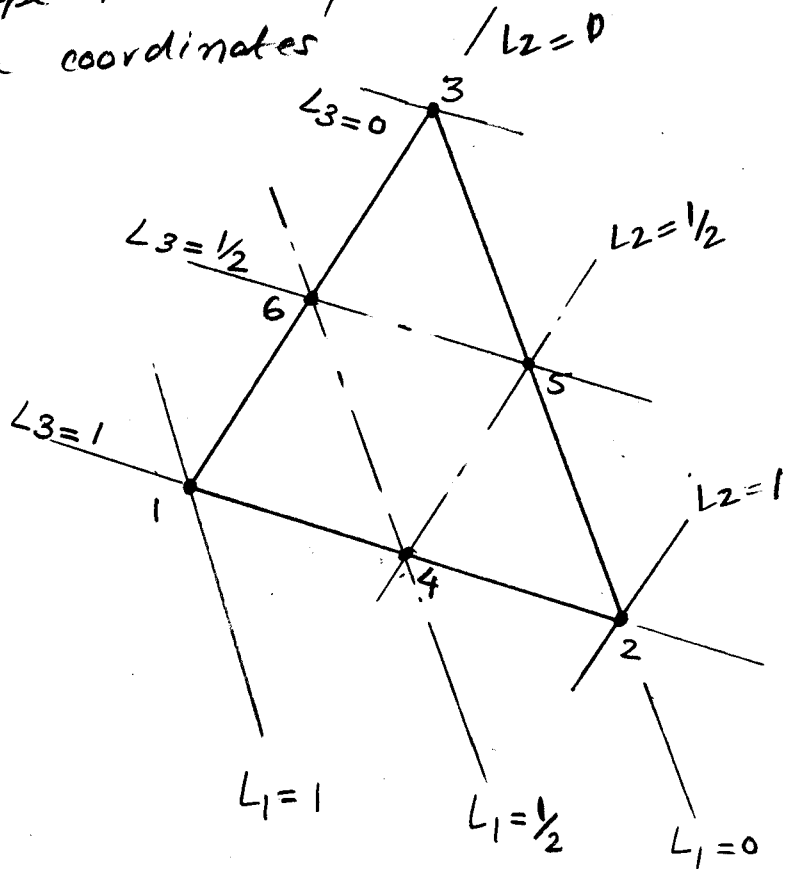




# Area Coordinates for Triangular Elements

## Example Problem

Find the shape Functions for the Six Noded Triangle in area coordinates  $L_2=0$



$$N_{a1} = \prod_{\substack{p=0 \\ p \neq K}}^K \frac{L_1 - L_{1,p}}{L_{1,1} - L_{1,p}}$$

$$N_{a1} = \frac{(L_1 - 0)(L_1 - \frac{1}{2})}{(1 - 0)(1 - \frac{1}{2})} = \frac{2L_1(2L_1 - 1)}{2(1)(2 - 1)} = L_1(2L_1 - 1)$$

$$N_{a1} \Big|_{\text{Node 1}} = 1(2 - 1) = 1 \quad \text{OK}$$

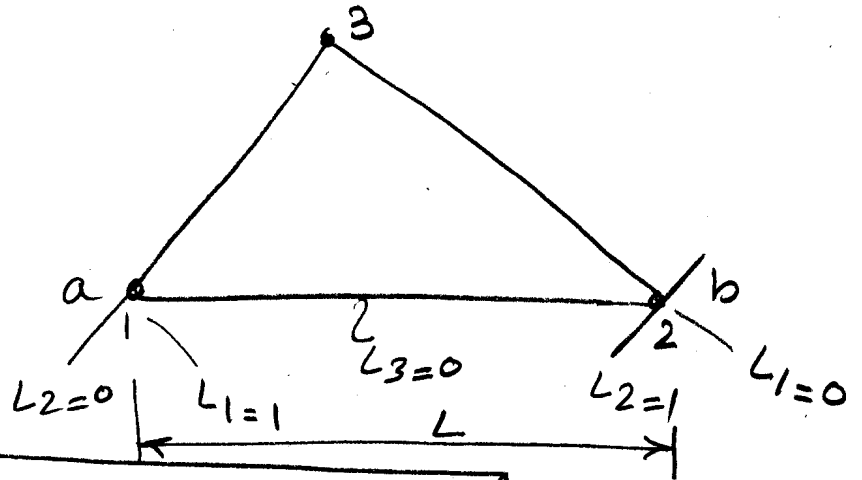
$$N_{a2} = \prod_{\substack{p=0 \\ p \neq K}}^K \frac{L_2 - L_{2,p}}{L_{2,2} - L_{2,p}}$$

$$N_{a2} = \frac{(L_2 - 0)(L_2 - \frac{1}{2})}{(1 - 0)(1 - \frac{1}{2})} = L_2(2L_2 - 1)$$

# Area Coordinates For Triangular Elements

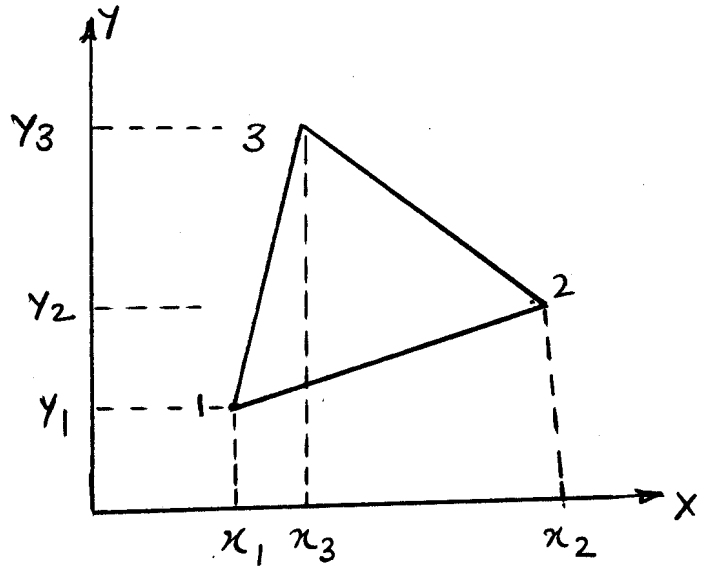
## Integration Formulas:

Usage of area coordinates facilitates integration of shape functions over line paths and areas.



$$\int_a^b L_1^k L_2^l dL = \frac{k! l!}{(1+k+l)!} \cdot L$$
$$\int_A L_1^k L_2^l L_3^m dA = 2A \frac{k! l! m!}{(2+k+l+m)}$$

## Area Coordinates For Triangular Elements



The area of the above Triangle  
is equal to

$$A = \text{Area } x_1 1 3 x_3 + \text{Area } x_3 3 2 x_2 - \text{Area } x_1 2 x_2$$

$$= (x_3 - x_1) \left( \frac{y_3 + y_1}{2} \right) + (x_2 - x_3) \left( \frac{y_3 + y_2}{2} \right) \\ - (x_2 - x_1) \left( \frac{y_2 + y_1}{2} \right)$$

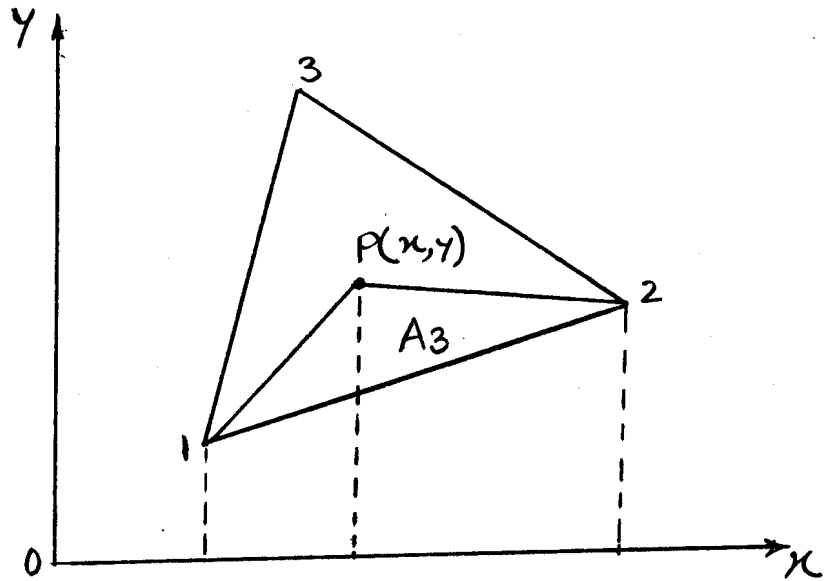
$$\Rightarrow 2A = y_1(x_3 - x_1 - x_2 + x_1) + y_2(x_2 - x_3 - x_2 + x_1) \\ + y_3(x_3 - x_1 + x_2 - x_3)$$

$$2A = y_1(x_3 - x_2) + y_2(x_1 - x_3) + y_3(x_2 - x_1)$$

$$\Rightarrow 2A = \text{Det} \begin{vmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{vmatrix}$$

## Area Coordinates For Triangular Elements

Now the area of any of the subtriangles  $A_1, A_2, A_3$  can be found in a similar way



$$2A_3 = \begin{vmatrix} 1 & x_1 & y_1 \\ 1 & x_2 & y_2 \\ 1 & x & y \end{vmatrix} = 1(x_1 y_2 - x_2 y_1) + x(y_1 - y_2) + y(x_2 - x_1)$$

$$x_1 y_2 - x_2 y_1 = \text{Det} \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} = \text{Twice the area of Triangle formed by Origin and pts 1 \& 2}$$

Thus we can write

$$2A_3 = 2A_{12} + y_{12}x + x_{21}y$$

Or in general

$$2A_i = 2A_{jk} + y_{jk}x + x_{kj}y$$

$$L_i = \frac{A_i}{A} = \frac{1}{2A} (2A_{jk} + y_{jk}x + x_{kj}y)$$

## Area Coordinates and Triangular Elements

Writing the previous expression for shape function in Area Coordinates in matrix form:

$$\begin{Bmatrix} L_1 \\ L_2 \\ L_3 \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} x_2 y_3 - x_3 y_2 & y_2 - y_3 & x_3 - x_2 \\ x_3 y_1 - x_1 y_3 & y_3 - y_1 & x_1 - x_3 \\ x_1 y_2 - x_2 y_1 & y_1 - y_2 & x_2 - x_1 \end{bmatrix} \begin{Bmatrix} 1 \\ x \\ y \end{Bmatrix}$$

→ Area Coordinate Shape Functions in cartesian Coords.

Inverse of above relation is:

$$\begin{Bmatrix} 1 \\ x \\ y \end{Bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{bmatrix} \begin{Bmatrix} L_1 \\ L_2 \\ L_3 \end{Bmatrix}$$

The first of above equations is the identity

$$L_1 + L_2 + L_3 = 1$$

The centroid of the triangle is at  $L_1 = L_2 = L_3 = \frac{1}{3}$

$$x_c = \frac{1}{3}(x_1 + x_2 + x_3), \quad y_c = \frac{1}{3}(y_1 + y_2 + y_3)$$

## Area Coordinates and Triangular Elements

Establishing relation between derivatives in area coordinates and cartesian coordinates.

By Chain Rule:

$$\frac{\partial f(L_1, L_2, L_3)}{\partial x} = \frac{\partial f}{\partial L_1} \frac{\partial L_1}{\partial x} + \frac{\partial f}{\partial L_2} \frac{\partial L_2}{\partial x} + \frac{\partial f}{\partial L_3} \frac{\partial L_3}{\partial x}$$

$$= \frac{1}{2A} \left[ (y_2 - y_3) \frac{\partial f}{\partial L_1} + (y_3 - y_1) \frac{\partial f}{\partial L_2} + (y_1 - y_2) \frac{\partial f}{\partial L_3} \right]$$

$$\frac{\partial f(L_1, L_2, L_3)}{\partial y} = \frac{\partial f}{\partial L_1} \frac{\partial L_1}{\partial y} + \frac{\partial f}{\partial L_2} \frac{\partial L_2}{\partial y} + \frac{\partial f}{\partial L_3} \frac{\partial L_3}{\partial y}$$

$$= \frac{1}{2A} \left[ (x_3 - x_2) \frac{\partial f}{\partial L_1} + (x_1 - x_3) \frac{\partial f}{\partial L_2} + (x_2 - x_1) \frac{\partial f}{\partial L_3} \right]$$

$$\begin{Bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} y_2 - y_3 & y_3 - y_1 & y_1 - y_2 \\ x_3 - x_2 & x_1 - x_3 & x_2 - x_1 \end{bmatrix} \begin{Bmatrix} \frac{\partial f}{\partial L_1} \\ \frac{\partial f}{\partial L_2} \\ \frac{\partial f}{\partial L_3} \end{Bmatrix}$$

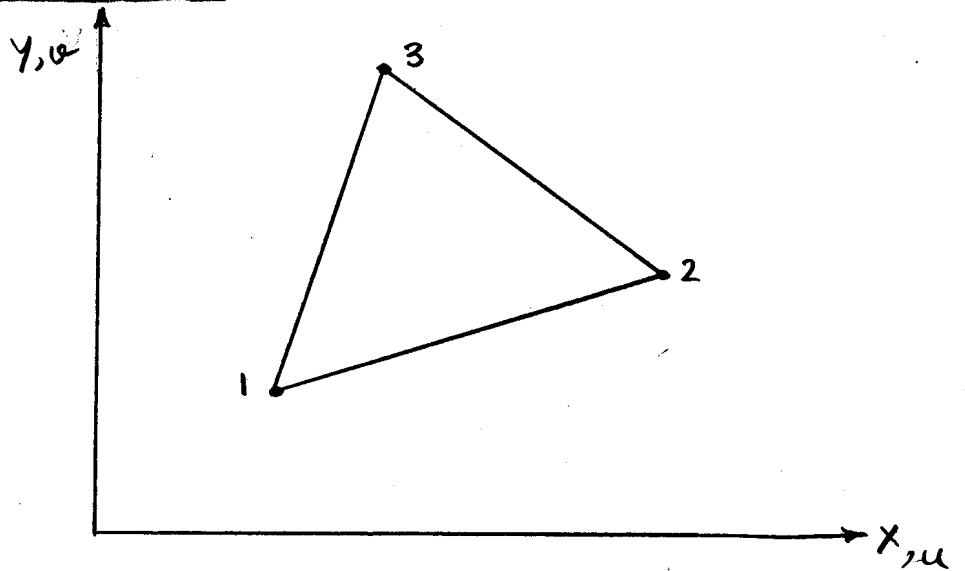
$$\begin{Bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix} \begin{Bmatrix} \frac{\partial f}{\partial L_1} \\ \frac{\partial f}{\partial L_2} \\ \frac{\partial f}{\partial L_3} \end{Bmatrix}$$

Where

$$x_{32} = x_3 - x_2$$

$$y_{23} = y_2 - y_3 \text{ etc}$$

# Constant Strain Triangle CST Using Area Coordinates



$$u = L_1 u_1 + L_2 u_2 + L_3 u_3$$

$$v = L_1 v_1 + L_2 v_2 + L_3 v_3$$

$$\begin{Bmatrix} u \\ v \end{Bmatrix} = \begin{bmatrix} L_1 & L_2 & L_3 & | & 0 & 0 & 0 \\ 0 & 0 & 0 & | & L_1 & L_2 & L_3 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ v_1 \\ v_2 \\ v_3 \end{Bmatrix}$$

2x6

$$u = N_a v$$

The Strains are given by:

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{bmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{bmatrix} \begin{Bmatrix} u \\ v \end{Bmatrix}$$

Now making use of relation

$$\begin{Bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix} \begin{Bmatrix} \frac{\partial f}{\partial L_1} \\ \frac{\partial f}{\partial L_2} \\ \frac{\partial f}{\partial L_3} \end{Bmatrix}$$

Constant Strain Triangle CST  
Using Area Coordinates

$$\frac{\partial u}{\partial x} = \frac{1}{2A} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} \end{bmatrix} \begin{Bmatrix} \frac{\partial u}{\partial L_1} \\ \frac{\partial u}{\partial L_2} \\ \frac{\partial u}{\partial L_3} \end{Bmatrix}$$

$$\frac{\partial u}{\partial x} = \frac{1}{2A} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} \end{bmatrix} \begin{Bmatrix} U_1 \\ U_2 \\ U_3 \end{Bmatrix}$$

$$\frac{\partial v}{\partial y} = \frac{1}{2A} \begin{bmatrix} X_{32} & X_{13} & X_{21} \end{bmatrix} \begin{Bmatrix} V_1 \\ V_2 \\ V_3 \end{Bmatrix}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \frac{1}{2A} \begin{bmatrix} X_{32} & X_{13} & X_{21} & Y_{23} & Y_{31} & Y_{12} \end{bmatrix} \begin{Bmatrix} U_1 \\ U_2 \\ U_3 \\ \hline V_1 \\ V_2 \\ V_3 \end{Bmatrix}$$

or in Matrix Form we can write

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{bmatrix} \frac{\partial}{\partial x} & 0 \\ 0 & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{bmatrix} \begin{Bmatrix} u \\ v \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} & 0 & 0 & 0 \\ 0 & 0 & 0 & X_{32} & X_{13} & X_{21} \\ X_{32} & X_{13} & X_{21} & Y_{23} & Y_{31} & Y_{12} \end{bmatrix} \begin{Bmatrix} U_1 \\ U_2 \\ U_3 \\ \hline V_1 \\ V_2 \\ V_3 \end{Bmatrix}$$

**B**  
STRAIN-DISPL MATRIX



## Constant Strain Triangle Using Area Coordinates

We can also write:

$$\epsilon_x = \frac{1}{2A} \sum_{i=1}^n b_i u_i$$

$$\epsilon_y = \frac{1}{2A} \sum_{i=1}^n a_i v_i$$

$$\gamma_{xy} = \frac{1}{2A} \sum_{i=1}^n (a_i u_i + b_i v_i)$$

Where,

$$b_1, b_2, b_3 = Y_{23}, Y_{31}, Y_{12}$$

$$a_1, a_2, a_3 = X_{32}, X_{13}, X_{21}$$

Now Element Stiffness  
Matrix

$$= K_e = \int_V B^T D B dv$$

$$= t \int_A B^T D B dA$$

$$K_e = \frac{t}{4A^2} \int_A \begin{bmatrix} Y_{23} & 0 & X_{32} \\ Y_{31} & 0 & X_{13} \\ Y_{12} & 0 & X_{21} \\ \hline 0 & X_{32} & Y_{23} \\ 0 & X_{13} & Y_{31} \\ 0 & X_{21} & Y_{12} \end{bmatrix} \begin{bmatrix} E_{11} & E_{12} & E_{13} \\ & E_{22} & E_{23} \\ \text{Sym.} & & E_{33} \end{bmatrix} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} & 0 & 0 & 0 \\ 0 & 0 & 0 & X_{32} & X_{13} & X_{21} \\ X_{32} & X_{13} & X_{21} & Y_{23} & Y_{31} & Y_{12} \end{bmatrix} dA$$

$6 \times 3$ 
 $3 \times 3$ 
 $3 \times 6$

## Constant Strain Triangle Using Area Coordinates

The previous expression for element stiffness matrix can be written as:

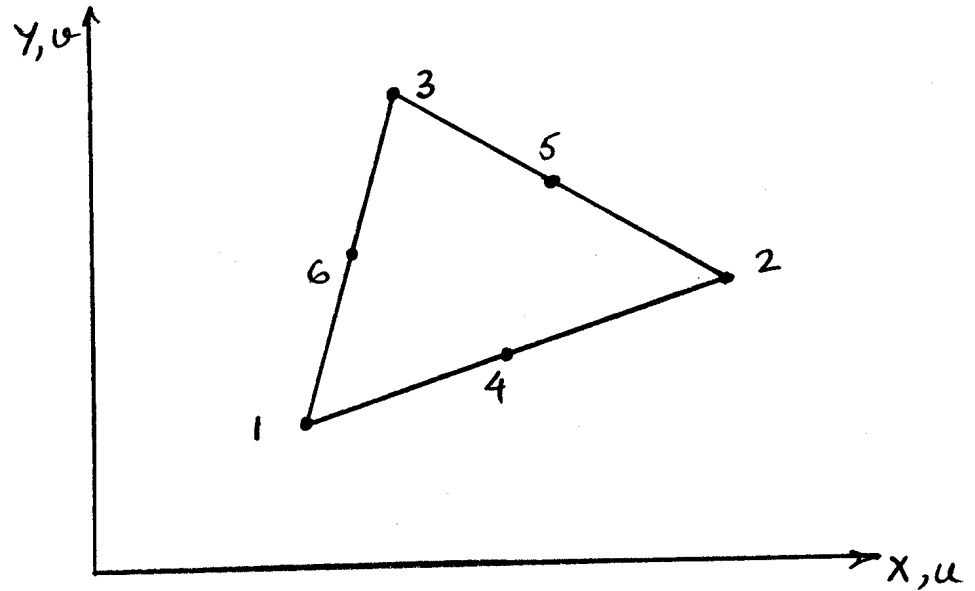
$$K_e = \begin{bmatrix} K_{uu} & K_{uv} \\ K_{uv}^T & K_{vv} \end{bmatrix}$$

3x3                      3x3  
3x3                      3x3

$$\left. \begin{aligned} K_{uu,ij} &= E_{11} b_i b_j + E_{33} a_i a_j + E_{13} (b_i a_j + b_j a_i) \\ K_{vv,ij} &= E_{33} b_i b_j + E_{22} a_i a_j + E_{23} (b_i a_j + b_j a_i) \\ K_{uv,ij} &= E_{13} b_i b_j + E_{23} a_i a_j + E_{12} b_i a_j + E_{33} a_i b_j \end{aligned} \right\} \frac{xt}{4A}$$

The above expression for element stiffness matrix yields the same/identical stiffness matrix obtained for CST element using Cartesian coordinates.

# LINEAR STRAIN TRIANGLE IN AREA COORDINATES



The Shape Function for 6-Noded LST have previously been derived and are summarized below for reference:

$$N_{a1} = L_1(2L_1 - 1)$$

$$N_{a2} = L_2(2L_2 - 1)$$

$$N_{a3} = L_3(2L_3 - 1)$$

$$N_{a4} = 4L_1L_2$$

$$N_{a5} = 4L_2L_3$$

$$N_{a6} = 4L_1L_3$$

$$\begin{Bmatrix} u \\ v \end{Bmatrix} = \begin{bmatrix} N_1 & N_2 & N_3 & N_4 & N_5 & N_6 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & N_1 & N_2 & N_3 & N_4 & N_5 & N_6 \end{bmatrix} \begin{Bmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \\ U_6 \\ \hline V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \\ V_6 \end{Bmatrix}$$

2x12

# LINEAR STRAIN TRIANGLE IN AREA COORDINATES

$$\epsilon_x = \frac{\partial u}{\partial x}$$

$$\epsilon_y = \frac{\partial v}{\partial y}$$

$$\gamma_{xy} = \frac{\partial v}{\partial y} + \frac{\partial u}{\partial x}$$

The above need to be converted to derivatives w.r.t area coordinates using the chain rule

$$\begin{Bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial y} \end{Bmatrix} = \frac{1}{2A} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} \\ X_{32} & X_{13} & X_{21} \end{bmatrix} \begin{Bmatrix} \frac{\partial u}{\partial L_1} \\ \frac{\partial u}{\partial L_2} \\ \frac{\partial u}{\partial L_3} \end{Bmatrix}$$

$$\frac{\partial u}{\partial x} = \frac{1}{2A} \begin{bmatrix} Y_{23} & Y_{31} & Y_{12} \end{bmatrix} \begin{Bmatrix} \frac{\partial}{\partial L_1} \\ \frac{\partial}{\partial L_2} \\ \frac{\partial}{\partial L_3} \end{Bmatrix} \begin{bmatrix} N_1 & \dots & N_6 & | & 0 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ \vdots \\ u_6 \end{Bmatrix}$$

$$\frac{\partial u}{\partial x} = \frac{1}{2A} \underbrace{\begin{bmatrix} Y_{23} & Y_{31} & Y_{12} \end{bmatrix}}_Y \underbrace{\begin{bmatrix} 4L_1-1 & 0 & 0 & 4L_2 & 0 & 4L_3 \\ 0 & 4L_2-1 & 0 & 4L_1 & 4L_3 & 0 \\ 0 & 0 & 4L_3-1 & 0 & 4L_2 & 4L_1 \end{bmatrix}}_{\psi} \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \end{Bmatrix}$$

3x6

# LINEAR STRAIN TRIANGLE IN AREA COORDINATES

Similarly,

$$\frac{\partial u}{\partial x} = \frac{1}{2A} \underbrace{\begin{bmatrix} X_{32} & X_{13} & X_{21} \end{bmatrix}}_X \begin{bmatrix} \psi \\ \psi \\ \psi \end{bmatrix}_{3 \times 6} \begin{Bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \end{Bmatrix}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \frac{1}{2A} \begin{bmatrix} X & | & Y \\ \hline & & \end{bmatrix}_{1 \times 6} \begin{bmatrix} \psi & | & 0 \\ \hline 0 & | & \psi \end{bmatrix}_{6 \times 12} \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \\ \hline v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \end{Bmatrix}$$

We can now write the Strain-Displacement Relation as:

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \frac{1}{2A} \underbrace{\begin{bmatrix} Y & | & 0 \\ \hline 0 & | & X \\ \hline X & | & Y \\ \hline & & \end{bmatrix}}_{3 \times 6} \begin{bmatrix} \psi_{3 \times 6} & | & 0 \\ \hline 0 & | & \psi_{3 \times 6} \end{bmatrix}_{6 \times 12} \begin{Bmatrix} u_1 \\ u_2 \\ \vdots \\ u_6 \\ \hline v_1 \\ v_2 \\ \vdots \\ v_6 \end{Bmatrix}$$

$[B]_{3 \times 12}$

$$[B]_{3 \times 12} = \frac{1}{2A} \begin{bmatrix} Y & | & 0 \\ \hline 0 & | & X \\ \hline X & | & Y \\ \hline & & \end{bmatrix}_{3 \times 6} \begin{bmatrix} \psi_{3 \times 6} & | & 0 \\ \hline 0 & | & \psi_{3 \times 6} \end{bmatrix}_{6 \times 12}$$

STRAIN-DISPLACEMENT MATRIX

$$[B] = \frac{1}{2A} \begin{bmatrix} y_{23} & y_{31} & y_{12} & 0 & 0 & 0 \\ 0 & 0 & 0 & x_{32} & x_{13} & x_{21} \\ x_{32} & x_{13} & x_{21} & y_{23} & y_{31} & y_{12} \end{bmatrix} \begin{bmatrix} 4L_1-1 & 0 & 0 & 4L_2 & 0 & 4L_3 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 4L_2-1 & 0 & 4L_1 & 4L_3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4L_3-1 & 0 & 4L_2 & 4L_1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 4L_1-1 & 0 & 0 & 4L_2 & 0 & 4L_3 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 4L_2-1 & 0 & 4L_1 & 4L_3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 4L_2-1 & 0 & 4L_2 & 4L_1 \end{bmatrix}$$

$$= \frac{1}{2A} \begin{bmatrix} y_{23}(4L_1-1) & y_{31}(4L_2-1) & y_{12}(4L_3-1) & 4(y_{23}L_2 + y_{31}L_1) & 4(y_{31}L_3 + y_{12}L_2) & 4(y_{23}L_3 + y_{12}L_1) & 0 & 0 & \dots \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \dots \\ x_{32}(4L_1-1) & x_{13}(4L_2-1) & x_{21}(4L_3-1) & 4(x_{32}L_2 + x_{13}L_1) & 4(x_{13}L_3 + x_{21}L_2) & 4(x_{32}L_3 + x_{21}L_1) & y_{23}(4L_1-1) & \dots \end{bmatrix}$$

$$B^T_{DB} = \begin{bmatrix} y_{23}(4L_1-1) & 0 & x_{32}(4L_1-1) \\ y_{31}(4L_2-1) & 0 & x_{13}(4L_2-1) \\ y_{12}(4L_3-1) & 0 & x_{21}(4L_3-1) \\ 4(y_{13}L_2 + y_{31}L_1) & 0 & 4(x_{32}L_2 + x_{13}L_1) \\ 4(y_{31}L_3 + y_{12}L_2) & 0 & 4(x_{13}L_3 + x_{21}L_2) \\ 4(y_{23}L_3 + y_{12}L_1) & 0 & 4(x_{32}L_3 + x_{21}L_1) \\ 0 & x_{32}(4L_1-1) & y_{23}(4L_1-1) \\ 0 & x_{13}(4L_2-1) & y_{31}(4L_2-1) \\ 0 & x_{21}(4L_3-1) & y_{12}(4L_3-1) \\ 0 & 4(x_{32}L_2 + x_{13}L_1) & 4(y_{23}L_2 + y_{31}L_1) \\ 0 & 4(x_{13}L_3 + x_{21}L_2) & 4(y_{31}L_3 + y_{12}L_2) \\ 0 & 4(x_{32}L_3 + x_{21}L_1) & 4(y_{23}L_3 + y_{12}L_1) \end{bmatrix} \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{12} & C_{22} & C_{23} \\ C_{13} & C_{23} & C_{33} \end{bmatrix} \begin{bmatrix} y_{23}(4L_1-1) & y_{31}(4L_2-1) & \dots \\ 0 & 0 & \dots \\ x_{32}(4L_1-1) & x_{13}(4L_2-1) & \dots \end{bmatrix}$$

Carrying through these operations

$$\frac{1}{4A^2} \mathbf{B}^T \mathbf{D} \mathbf{B} = \begin{bmatrix} (y_{23}^2 c_{11} + 2y_{23}x_{32}c_{13} + x_{32}^2 c_{33})(4L_1 - 1)^2 & (y_{23}y_{31}c_{11} + (y_{31}x_{32} + y_{23}x_{13})c_{13} + x_{13}x_{32}c_{33})(4L_1 - 1)(4L_2 - 1) & & & \\ (y_{23}y_{31}c_{11} + (y_{23}x_{13} + x_{32}y_{31})c_{13} + x_{13}x_{32}c_{33})(4L_1 - 1)(4L_2 - 1) & (y_{31}^2 c_{11} + 2y_{31}x_{13}c_{13} + x_{13}^2 c_{33})(4L_2 - 1)^2 & & & \\ & & \cdot & & \\ & & \cdot & & \\ & & \cdot & & \\ & & \cdot & & \\ & & \cdot & & \end{bmatrix}$$

The resulting 12 x 12 matrix is then integrated term by term to obtain the desired stiffness matrix.

The process can be simplified, in terms of the integrations required, by using the concept of natural stiffness (i.e. computing stiffness with respect to generalized coordinates which have rigid body motions removed). In this particular case, we use the strains at the vertices of the triangle. Since the strains are linear,

$$\epsilon_x = L_1 \epsilon_{x_1} + L_2 \epsilon_{x_2} + L_3 \epsilon_{x_3} \quad \text{etc.} \quad \epsilon_{x_1} \equiv \epsilon_x \text{ at node 1 etc.}$$

$$\text{where } \{\epsilon_i\} = [\epsilon_{x_1} \quad \epsilon_{x_2} \quad \epsilon_{x_3} \quad \epsilon_{y_1} \quad \epsilon_{y_2} \quad \epsilon_{y_3} \quad \gamma_{xy_1} \quad \gamma_{xy_2} \quad \gamma_{xy_3}]^T$$

This can be written more concisely as

$$\{\epsilon\} = \begin{bmatrix} \bar{N} & 0 & 0 \\ 0 & \bar{N} & 0 \\ 0 & 0 & \bar{N} \end{bmatrix} \{\epsilon_i\}; \quad [\bar{N}]_{1 \times 3} = [L_1 \quad L_2 \quad L_3]$$

The corner strains are now related to the nodal displacements by

$$\{\epsilon_1\} = \frac{1}{2A} \begin{bmatrix} b\psi_1 & 0 \\ b\psi_2 & 0 \\ b\psi_3 & 0 \\ \hline 0 & a\psi_1 \\ 0 & a\psi_2 \\ 0 & a\psi_3 \\ \hline a\psi_1 & b\psi_1 \\ a\psi_2 & b\psi_2 \\ a\psi_3 & b\psi_3 \end{bmatrix} \{u\}$$

\*{u} listed  
 $[u_1, u_2, v_1, \dots, v_3]^T$

where

$$[b] \equiv [y_{23} \ y_{31} \ y_{12}] = [b_1 \ b_2 \ b_3]$$

$$[a] = [x_{32} \ x_{13} \ x_{21}] = [a_1 \ a_2 \ a_3]$$

and  $[\psi_1]$  is  $[\psi]$  evaluated at node 1, etc.

or

$$\{\epsilon_1\} = [T]\{u\}$$

9x12   12x1

thus,

$$\{\epsilon\} = [\phi_\epsilon][T]\{u\}$$

3x9   9x12   12x1

[B]<sub>3x12</sub>

$$[k] = t[T]^T \int_A \underbrace{[\phi_\epsilon]^T [D] [\phi_\epsilon]}_{\text{This is the natural stiffness 9x9 (Three rigid body motions removed)}} dA [T]$$

This is the natural stiffness 9x9 (Three rigid body motions removed)



In general case

$$[D] = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ & c_{22} & c_{23} \\ \text{Symm.} & & c_{33} \end{bmatrix}$$

$$[\phi_e]^T [D] [\phi_e] = \begin{bmatrix} c_{11} \bar{N}^T \bar{N} & | & c_{12} \bar{N}^T \bar{N} & | & c_{13} \bar{N}^T \bar{N} \\ & | & & | & \\ & | & c_{22} \bar{N}^T \bar{N} & | & c_{23} \bar{N}^T \bar{N} \\ & | & & | & \\ & | & & | & c_{33} \bar{N}^T \bar{N} \end{bmatrix}$$

the only integration which must be performed is

$$\int_A [\bar{N}^T \bar{N}] dA$$

3x3

$$[\bar{N}]^T [\bar{N}] = \begin{bmatrix} L_1^2 & L_1 L_2 & L_1 L_3 \\ & L_2^2 & L_2 L_3 \\ \text{Symm} & & L_3^2 \end{bmatrix} \quad \int_A L_1^2 dA = \frac{A}{6}$$

$$\int_A L_1 L_2 dA = \frac{A}{12}$$

thus  $\int_A [\phi_e]^T [D] [\phi_e] dA$

$$= \frac{A}{12} \begin{bmatrix} c_{11} Q & | & c_{12} Q & | & c_{13} Q \\ \hline & | & c_{22} Q & | & c_{33} Q \\ \text{Symm} & & & | & c_{33} Q \end{bmatrix}; \quad [Q]_{3 \times 3} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

Partition [T] into  $\frac{1}{2A} \begin{bmatrix} [U] & [O] \\ [O] & [V] \\ [V] & [U] \end{bmatrix} \quad [U], [V]_{3 \times 3}$

$$\text{then } [k] = \frac{t}{48A} \begin{bmatrix} U^T & 0 & V^T \\ 0 & V^T & U^T \end{bmatrix} \begin{bmatrix} C_{11} Q & C_{12} Q & C_{13} Q \\ & C_{22} Q & C_{23} Q \\ \text{Symm} & & C_{33} Q \end{bmatrix} \begin{bmatrix} U & 0 \\ 0 & V \\ V & U \end{bmatrix}$$

this given on following page

$$[U] = \begin{bmatrix} b\psi_1 \\ b\psi_2 \\ b\psi_3 \end{bmatrix}_{3 \times 6} = \begin{bmatrix} 3b_1 & -b_2 & -b_3 & 4b_2 & 0 & 4b_3 \\ -b_1 & 3b_2 & -b_3 & 4b_1 & 4b_3 & 0 \\ -b_1 & -b_2 & 3b_3 & 0 & 4b_2 & 4b_1 \end{bmatrix} \begin{matrix} b_1 = y_{23} \\ b_2 = y_{31} \\ b_3 = y_{13} \\ a_1 = x_{32} \\ a_2 = x_{13} \\ a_3 = x_{21} \end{matrix}$$

$[V]$  is obtained from  $[U]$  by substituting  $a_1$  for  $b_1$ ,  $a_2$  for  $b_2$ , and  $a_3$  for  $b_3$ .

The matrix product when multiplied out gives

$$[k_{uu}] = \frac{t}{48A} [C_{11} U^T Q U + C_{13} (V^T Q U + U^T Q V) + C_{33} V^T Q V]$$

$$[k_{uv}] = \frac{t}{48A} [C_{13} U^T Q U + C_{12} U^T Q V + C_{33} V^T Q U + C_{23} V^T Q V]$$

$$[k_{vv}] = \frac{t}{48A} [C_{22} V^T Q V + C_{23} (U^T Q V + V^T Q U) + C_{33} U^T Q U]$$

$$[k] = \begin{bmatrix} [k_{uu}] & [k_{uv}] \\ \text{Symm.} & [k_{vv}] \end{bmatrix} \quad \begin{matrix} \text{*order of listing} \\ \{u\} = u_1, \dots, u_6, v_1, \dots, v_6^T \end{matrix}$$

For isotropic material  $C_{11} = C_{22} = \frac{E}{1-\nu^2}$ ,  $C_{12} = \nu C_{11}$ ,  $C_{33} = \frac{(1-\nu)}{2} C_{11}$

$$C_{13} = C_{23} = 0.$$

Stiffness matrix for LST element of constant thickness  $h$  :

$$K = \frac{h}{48 \Delta} \begin{bmatrix} \begin{array}{ccc|ccc} \beta_1 & -\beta_1 & -\beta_1 & \cdot & \cdot & \cdot \\ -\beta_2 & \beta_2 & -\beta_2 & \cdot & \cdot & \cdot \\ -\beta_3 & -\beta_3 & \beta_3 & \cdot & \cdot & \cdot \\ \alpha_2 & \alpha_1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & \alpha_3 & \alpha_2 & \cdot & \cdot & \cdot \\ \alpha_3 & \cdot & \alpha_1 & \cdot & \cdot & \cdot \end{array} & \begin{array}{ccc} \beta_1 & -\alpha_1 & -\alpha_1 \\ -\alpha_2 & \beta_2 & -\alpha_2 \\ -\alpha_3 & -\alpha_3 & \beta_3 \\ \alpha_2 & \alpha_1 & \cdot \\ \cdot & \alpha_3 & \alpha_2 \\ \alpha_3 & \cdot & \alpha_1 \end{array} \\ \hline \begin{array}{ccc|ccc} \cdot & \cdot & \cdot & \beta_1 & -\beta_1 & -\beta_1 \\ \cdot & \cdot & \cdot & -\alpha_2 & \beta_2 & -\alpha_2 \\ \cdot & \cdot & \cdot & -\alpha_3 & -\alpha_3 & \beta_3 \\ \cdot & \cdot & \cdot & \alpha_2 & \alpha_1 & \cdot \\ \cdot & \cdot & \cdot & \cdot & \alpha_3 & \alpha_2 \\ \cdot & \cdot & \cdot & \cdot & \alpha_3 & \cdot \end{array} & \begin{array}{ccc} \beta_1 & -\beta_1 & -\beta_1 \\ -\alpha_2 & \beta_2 & -\alpha_2 \\ -\alpha_3 & -\alpha_3 & \beta_3 \\ \alpha_2 & \alpha_1 & \cdot \\ \cdot & \alpha_3 & \alpha_2 \\ \cdot & \alpha_3 & \cdot \end{array} \end{bmatrix}$$
  

$$\begin{bmatrix} 2e_{11} & e_{11} & e_{11} & 2e_{12} & e_{12} & e_{12} & 2e_{15} & e_{15} & e_{15} \\ 2e_{11} & e_{11} & \cdot & e_{12} & 2e_{12} & e_{12} & e_{15} & 2e_{15} & e_{15} \\ 2e_{11} & \cdot & \cdot & e_{12} & e_{12} & 2e_{12} & e_{15} & e_{15} & 2e_{15} \\ \cdot & \cdot & \cdot & 2e_{22} & e_{22} & e_{22} & 2e_{25} & e_{25} & e_{25} \\ \cdot & \cdot & \cdot & 2e_{22} & e_{22} & \cdot & 2e_{25} & 2e_{25} & e_{25} \\ \cdot & \cdot & \cdot & 2e_{22} & \cdot & \cdot & 2e_{25} & e_{25} & 2e_{25} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 2e_{33} & e_{33} & e_{33} \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 2e_{33} & e_{33} & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 2e_{33} & \cdot & e_{33} \end{bmatrix}$$

SYMMETRIC

$$\begin{bmatrix} \beta_1 & -\beta_2 & -\beta_3 & \alpha_2 & \cdot & \alpha_3 & \cdot & \cdot & \cdot & \cdot \\ -\beta_1 & \beta_2 & -\beta_3 & \alpha_1 & \alpha_3 & \cdot & \cdot & \cdot & \cdot & \cdot \\ -\beta_1 & -\beta_2 & \beta_3 & \cdot & \alpha_2 & \alpha_1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \beta_1 & -\alpha_2 & -\alpha_3 & \alpha_2 & \cdot & \alpha_3 \\ \cdot & \cdot & \cdot & -\alpha_1 & \beta_2 & -\alpha_3 & \alpha_1 & \alpha_3 & \cdot \\ \cdot & \cdot & \cdot & -\alpha_1 & -\alpha_2 & \beta_3 & \cdot & \alpha_2 & \alpha_1 \\ \cdot & \cdot & \cdot & \beta_1 & -\alpha_2 & -\alpha_3 & \alpha_2 & \cdot & \alpha_3 \\ -\alpha_1 & \beta_2 & -\alpha_3 & \alpha_1 & \alpha_3 & \cdot & -\beta_1 & \beta_2 & -\beta_3 & \alpha_1 & \alpha_3 \\ -\alpha_1 & -\alpha_2 & \beta_3 & \cdot & \alpha_2 & \alpha_1 & -\beta_1 & -\beta_2 & \beta_3 & \cdot & \alpha_2 & \alpha_1 \end{bmatrix}$$

(III-29)

The nodal displacement vector is arranged as follows:

$$r^T = \langle u_1 \ u_2 \ u_3 \ u_4 \ u_5 \ u_6 \ ; \ v_1 \ v_2 \ v_3 \ v_4 \ v_5 \ v_6 \rangle$$

with isotropic material

$$C_{11} = C_{22} = E / (1 - \nu^2)$$

$$C_{12} = \nu E / (1 - \nu^2)$$

$$C_{33} = (1 - \nu) E / (2(1 - \nu^2))$$

$$C_{13} = C_{23} = 0$$

$$[k_{uu}]_{6 \times 6} = \frac{Et}{48A(1-\nu^2)} [U^T Q U + \left(\frac{1-\nu}{2}\right) V^T Q V]$$

$$[k_{uv}]_{6 \times 6} = \frac{Et}{48A(1-\nu^2)} [\nu U^T Q V + \left(\frac{1-\nu}{2}\right) V^T Q U]$$

$$[k_{vv}]_{6 \times 6} = \frac{Et}{48A(1-\nu^2)} [V^T Q V + \left(\frac{1-\nu}{2}\right) U^T Q U]$$

Only 3 matrices,  $U^T Q U$ ,  $V^T Q V$ ,  $U^T Q V$  of relatively small order need to be evaluated.

#### Triangular element

$$K_{11} = 12 b_1^2 + 6(1-\nu) a_1^2$$

$$K_{21} = \nu 12 a_1 b_1 + 6(1-\nu) a_1 b_1$$

$$K_{31} = -4 b_1 b_2 - 2(1-\nu) a_1 a_2$$

$$K_{41} = -4 a_2 b_1 - 2(1-\nu) a_1 b_2$$

$$K_{51} = -4 b_1 b_3 - 2(1-\nu) a_1 a_3$$

$$K_{61} = -4 \nu a_3 b_1 - 2(1-\nu) a_1 b_3$$

$$K_{71} = 16 b_1 b_2 + 8(1-\nu) a_1 a_2$$

$$K_{81} = 16 \nu a_2 b_1 + 8(1-\nu) a_1 b_2$$

$$K_{91} = 0$$

$$K_{101} = 16 \nu a_3 b_1 + 8(1-\nu) a_1 b_2$$

$$K_{111} = 16 b_1 b_3 + 8(1-\nu) a_1 a_3$$

$$K_{121} = 16 \nu b_1 a_3 + 8(1-\nu) a_1 b_3$$

$$K_{22} = 12 a_1^2 + 6(1-\nu) b_1^2$$

$$K_{32} = 4 \nu a_1 b_2 - 2(1-\nu) b_1 a_2$$

$$\begin{aligned}
K_{42} &= -4 a_1 a_2 - 2(1-\nu) b_1 b_2 \\
K_{52} &= -4 \nu a_1 b_3 - 2(1-\nu) b_1 a_3 \\
K_{62} &= -4 a_1 a_3 - 2(1-\nu) b_1 b_3 \\
K_{72} &= 16 \nu a_1 b_2 + 8(1-\nu) b_1 a_2 \\
K_{82} &= 16 a_1 a_2 + 8(1-\nu) b_1 b_2 \\
K_{92} &= 0 \\
K_{102} &= 0 \\
K_{112} &= 16 \nu a_1 b_3 + 8(1-\nu) b_1 a_3 \\
K_{122} &= 16 a_1 a_3 + 8(1-\nu) b_1 b_3 \\
K_{33} &= 12b_2^2 + 6(1-\nu) a_2^2 \\
K_{43} &= 12 \nu a_2 b_2 + 6(1-\nu) b_2 a_2 \\
K_{53} &= -4 b_2 b_3 - 2(1-\nu) a_2 a_3 \\
K_{63} &= -4 \nu a_3 b_2 - 2(1-\nu) b_3 a_2 \\
K_{73} &= 16 b_1 b_2 + 8(1-\nu) a_1 a_2 \\
K_{83} &= 16 \nu a_1 b_2 + 8(1-\nu) b_1 a_2 \\
K_{93} &= 16 b_2 b_3 + 8(1-\nu) a_2 a_3 \\
K_{103} &= 16 \nu a_3 b_2 + 8(1-\nu) b_3 a_2 \\
K_{113} &= 0 \\
K_{123} &= 0 \\
K_{44} &= 12 a_2^2 + 6(1-\nu) b_2^2 \\
K_{54} &= -4 \nu a_2 b_3 - 2(1-\nu) b_2 a_3
\end{aligned}$$

$$\begin{aligned}
K_{64} &= -4 a_3 a_2 - 2(1-\nu) b_3 b_2 \\
K_{74} &= 16 \nu a_2 b_1 + 8(1-\nu) b_2 a_1 \\
K_{84} &= 16 a_1 a_2 + 8(1-\nu) b_1 b_2 \\
K_{94} &= 16 \nu a_2 b_3 + 8(1-\nu) b_2 a_3 \\
K_{104} &= 16 a_2 a_3 + 8(1-\nu) b_2 b_3 \\
K_{114} &= 0 \\
K_{124} &= 0 \\
K_{55} &= 12 b_3^2 + 6(1-\nu) a_3^2 \\
K_{65} &= 12 \nu a_3 b_3 + 6(1-\nu) b_3 a_3 \\
K_{75} &= 0 \\
K_{85} &= 0 \\
K_{95} &= 16 b_2 b_3 + 8(1-\nu) a_2 a_3 \\
K_{105} &= 16 \nu a_2 b_3 + 8(1-\nu) b_2 a_3 \\
K_{115} &= 16 b_1 b_3 + 8(1-\nu) a_1 a_3 \\
K_{125} &= 16 \nu a_1 b_3 + 8(1-\nu) b_1 a_3 \\
K_{66} &= 12 a_3^2 + 6(1-\nu) b_3^2 \\
K_{76} &= 0 \\
K_{86} &= 0 \\
K_{96} &= 16 \nu a_3 b_2 + 8(1-\nu) b_3 a_2 \\
K_{106} &= 16 a_2 a_3 + 8(1-\nu) b_2 b_3
\end{aligned}$$

$$\begin{aligned}
K_{116} &= 16 v b_1 a_3 + 8(1-v) a_1 b_3 \\
K_{126} &= 16 a_1 a_3 + 8(1-v) b_1 b_3 \\
K_{77} &= 32 (b_2^2 + b_1 b_2 + b_1^2) + (1-v) 16 (a_2^2 + a_1 a_2 + a_1^2) \\
K_{87} &= 16 v (2a_2 b_2 + a_1 b_2 + a_2 b_1 + 2 a_1 b_1) + 8(1-v) (2b_2 a_2 + b_1 a_2 + b_2 a_1 + 2b_1 a_1) \\
K_{97} &= 16 (b_2 b_3 + b_2^2 + 2b_1 b_3 + b_1 b_2) + 8(1-v) (a_2 a_3 + a_2^2 + 2a_1 a_3 + a_1 a_2) \\
K_{107} &= 16 v (b_2 a_3 + a_2 b_2 + 2b_1 a_3 + b_1 a_2) + 8(1-v) (a_2 b_3 + b_1 a_2 + 2a_1 b_3 + a_1 b_2) \\
K_{117} &= 16 (2b_2 b_3 + b_1 b_2 + b_1 b_3 + b_1^2) + 8(1-v) (2a_2 a_3 + a_1 a_2 + a_1 a_3 + a_1^2) \\
K_{127} &= 16 v (2a_3 b_2 + a_1 b_2 + a_3 b_1 + b_1 a_1) + 8(1-v) (2b_3 a_2 + b_1 a_2 + b_3 a_1 + a_1 b_1) \\
K_{88} &= 32 (a_2^2 + a_1 a_2 + a_1^2) + 16(1-v) (b_2^2 + b_1 b_2 + b_1^2) \\
K_{98} &= 16 v (a_2 b_3 + b_2 a_2 + 2a_1 b_3 + a_1 b_2) + 8(1-v) (b_2 a_3 + a_2 b_2 + 2b_1 a_3 + b_1 a_2) \\
K_{108} &= 16 (a_3 a_2 + a_2^2 + 2a_1 a_3 + a_1 a_2) + 8(1-v) (b_3 b_2 + b_2^2 + 2 b_1 b_3 + b_1 b_2) \\
K_{118} &= 16 v (2a_2 b_3 + b_1 a_2 + a_1 b_3 + a_1 b_1) + 8(1-v) (2b_2 a_3 + a_1 b_2 + b_1 a_3 + b_1 a_1) \\
K_{128} &= 16 (2a_2 a_3 + a_1 a_2 + a_1 a_3 + a_1^2) + 8(1-v) (2b_2 b_3 + b_1 b_2 + b_1 b_3 + b_1^2) \\
K_{99} &= 32 (b_3^2 + b_1 b_3 + b_2^2) + 16(1-v) (a_3^2 + a_2 a_3 + a_1^2) \\
K_{109} &= 16 v (2a_3 b_3 + a_2 b_3 + a_3 b_2 + 2a_2 b_2) + 8(1-v) (2b_3 a_3 + b_2 a_3 + b_3 a_2 + 2b_2 a_2) \\
K_{119} &= 16 (b_3^2 + b_1 b_3 + b_2 b_3 + 2b_1 b_2) + 8(1-v) (a_3^2 + a_1 a_3 + 2a_1 a_2) \\
K_{129} &= 16 v (a_3 b_3 + a_1 b_3 + a_3 b_2 + 2a_1 b_2) + 8(1-v) (b_3 a_3 + b_1 a_3 + b_3 a_2 + 2b_1 a_2) \\
K_{1010} &= 32 (a_3^2 + a_2 a_3 + a_2^2) + 16(1-v) (b_3^2 + b_2 b_3 + b_2^2) \\
K_{1110} &= 16 v (a_3 b_3 + b_1 a_3 + a_2 b_3 + 2a_2 b_1) + 8(1-v) (b_3 a_3 + a_1 b_3 + b_2 a_3 + 2b_2 a_1) \\
K_{1210} &= 16 (a_3^2 + a_1 a_3 + a_2 a_3 + 2a_1 a_2) + 8(1-v) (b_3^2 + b_1 b_3 + b_2 b_3 + 2b_1 b_2)
\end{aligned}$$

$$K_{1211} = 16\nu(2_3b_3 + a_1b_3 + a_3b_1 + 2a_1b_1) + 8(1-\nu)(2b_3a_3 + b_1a_3 + b_3a_1 + 2b_1a_1)$$

$$K_{1212} = 32(a_3^2 + a_1a_3 + a_1^2) + 16(1-\nu)(b_3^2 + b_1b_3 + b_1^2)$$

The matrix is on the form

$F_{1x}$	$K_{11}$			...	$u_1$
$F_{1y}$	$K_{21}$	$K_{22}$		...	$v_1$
$F_{2x}$	$K_{31}$	$K_{32}$	$K_{33}$	...	$u_2$
	$\vdots$	$\vdots$	$\vdots$		$v_2$
	$\vdots$	$\vdots$	$\vdots$		

$$\frac{Et}{48A(1-\nu^2)}$$

$t = \text{thickness}$

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